

MEH329
DIGITAL SIGNAL PROCESSING

-4-

Discrete Time Systems-2

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Linear Constant-Coefficient Difference Equations (LCCDE)

- We calculate the output (response) of an LTI system using the input and the system's impulse response
- However, as n gets larger, the convolution sum results in increased computation time and memory requirement
- Systems for which the output can be represented in terms of the input signal's present and past values and the output signal's past values reduce these requirements

Linear Constant-Coefficient Difference Equations (LCCDE)

- An important class of LTI systems consists of those systems for which the input $x[n]$ and output $y[n]$ satisfy **Nth-order** eq. form of:

$$\sum_{k=0}^N a_k y[n-k] = \sum_{m=0}^M b_m x[n-m]$$

Linear Constant-Coefficient Difference Equations

$$a_0 y[n] + \sum_{k=1}^N a_k y[n-k] = \sum_{m=0}^M b_m x[n-m]$$

$$y[n] = \frac{1}{a_0} \left(\sum_{m=0}^M b_m x[n-m] - \sum_{k=1}^N a_k y[n-k] \right)$$

- If we choose $a_0=1$;

$$y[n] = \sum_{m=0}^M b_m x[n-m] - \sum_{k=1}^N a_k y[n-k]$$

- All systems cannot be represented in terms of an LCCD

Linear Constant-Coefficient Difference Equations

If the output is not related with the previous output values:

As a special case, if the output of the system does not depend on past output values:

$$y[n] = \sum_{m=0}^M b_m x[n-m]$$

$$h[n] = \sum_{m=0}^M b_m \delta[n-m]$$

Linear Constant-Coefficient Difference Equations

Sistemin dürtü yanıtı doğrudan giriş değerlerinin katsayıları olarak bulunduğu LCCDE gösterimikonvolusyon toplamına dönüşmektedir.

$$y[n] = \sum_{k=0}^M b_k x[n - k] = \sum_{k=0}^M h[k] x[n - k]$$

- Sistem çıkışının sadece giriş değerlerine bağlı olduğu bu sistemlerde LCCDE ile konvolusyon toplamının sonucu aynıdır.
- Sistemin dürtü yanıtı sonlu sayıda sıfırdan farklı değerlere sahip olduğu için bu tür sistemler yapı itibarıyla FIR sistemlerdir.
- The length of impulse response is **$M+1$** (FIR)

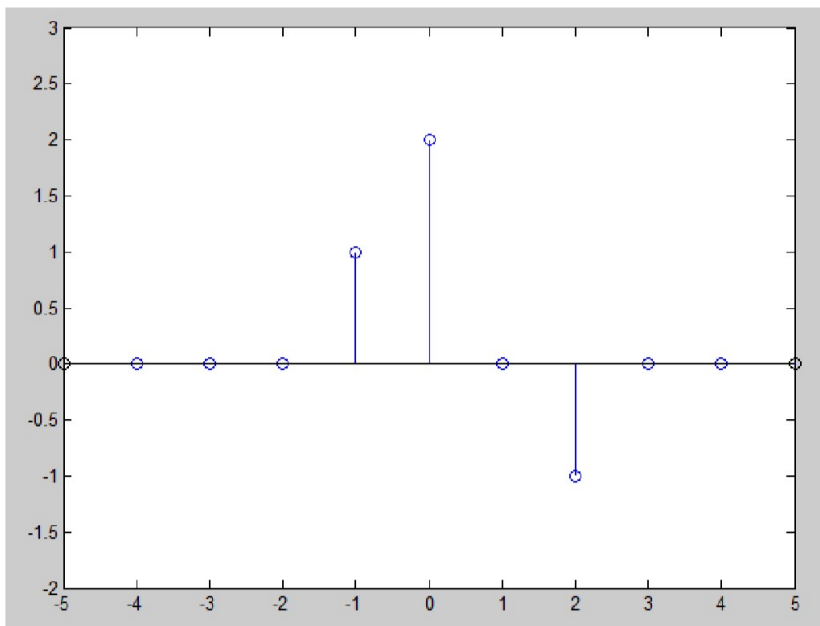
Linear Constant-Coefficient Difference Equations

- Example:
$$y[n] = x[n] - x[n-1]$$
$$x[n] = \left\{ 2, \underset{\substack{\uparrow \\ n=0}}{1}, 0, -1, -2, 1 \right\}$$

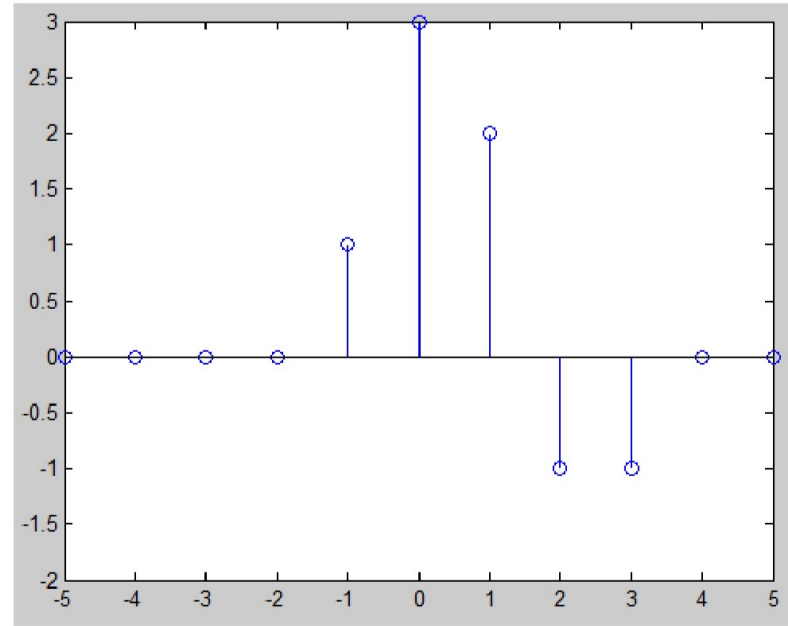
$n < -1$:	$x[n]=0$ and $y[n]=0$
$n = -1$:	$y[-1]=x[-1]-x[-2]=2$
$n = 0$:	$y[0]=x[0]-x[-1]=-1$
$n = 1$:	$y[1]=x[1]-x[0]=-1$
$n = 2$:	$y[2]=x[2]-x[1]=-1$
$n = 3$:	$y[3]=x[3]-x[2]=-1$
$n = 4$:	$y[4]=x[4]-x[3]=3$
$n = 5$:	$y[5]=x[5]-x[4]=-1$
$n > 5$:	$y[n]=0$

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$X[n]$



$y[n]$



Linear Constant-Coefficient Difference Equations

- Özyinesiz(Non-Recursive): Bir sistem LCCDE şeklinde tanımlandığında sistem çıkışı girişin o andaki ve eski değerlerine bağlı ise
- Özyineli (Recursive): Bir sistem LCCDE şeklinde tanımlandığında sistem çıkışı girişin o andaki ve eski değerlerine ek olarak çıkışın da eski değerlerine bağlı ise
- Recursive sistemlerde giriş değerleri yanında çıkışın başlangıç koşulları da verilmelidir.
- Başlangıç koşulları sistemin çalışma biçimine doğrudan etkisi bulunduğu için önemlidir.

LCCDE

- Example: Find the output of the accumulator system

$$y[n] = \sum_{k=-\infty}^n x[k]$$

$$y[n] = x[n] + \sum_{k=-\infty}^{n-1} x[k]$$

LCCDE representation

$$y[n] = x[n] + y[n-1]$$

$$y[n] - y[n-1] = x[n] \longrightarrow$$

$$N = 1$$

$$a_0 = 1$$

$$a_1 = -1$$

$$b_0 = 1$$

Linear Constant-Coefficient Difference Equations

$$x[n] = \left\{ \underset{\substack{\uparrow \\ n=0}}{1}, 0, -1, -2, 1 \right\}$$

- We need an initial value for y

$$y[0] = y[-1] + x[0]$$

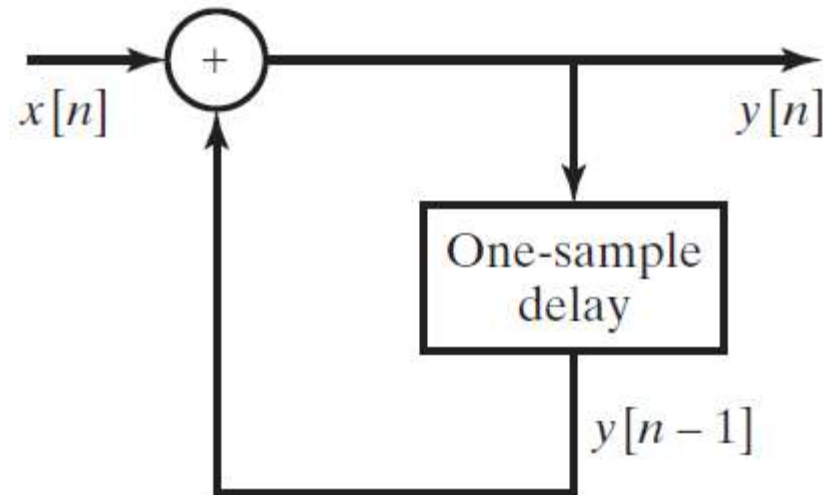
- If the system start with $y[-1]=0$

Linear Constant-Coefficient Difference Equations

$$\begin{aligned}n < 0 & : y[n]=0 \\n = 0 & : y[0]=x[0]+y[-1]=1 \\n = 1 & : y[1]=x[1]+y[0]=1 \\n = 2 & : y[2]=x[2]+y[1]=0 \\n = 3 & : y[3]=x[3]+y[2]=-2 \\n = 4 & : y[4]=x[4]+y[3]=-1 \\n = 5 & : y[5]=x[5]+y[4]=-1 \\n > 5 & : y[n]=-1\end{aligned}$$

Linear Constant-Coefficient Difference Equations

- Block diagram of the accumulator:



Linear Constant-Coefficient Difference Equations

- Example: Moving-average system

$$y[n] = \frac{1}{M_1 + M_2 + 1} \sum_{k=-M_1}^{M_2} x[n-k]$$

with $M_1 = 0$

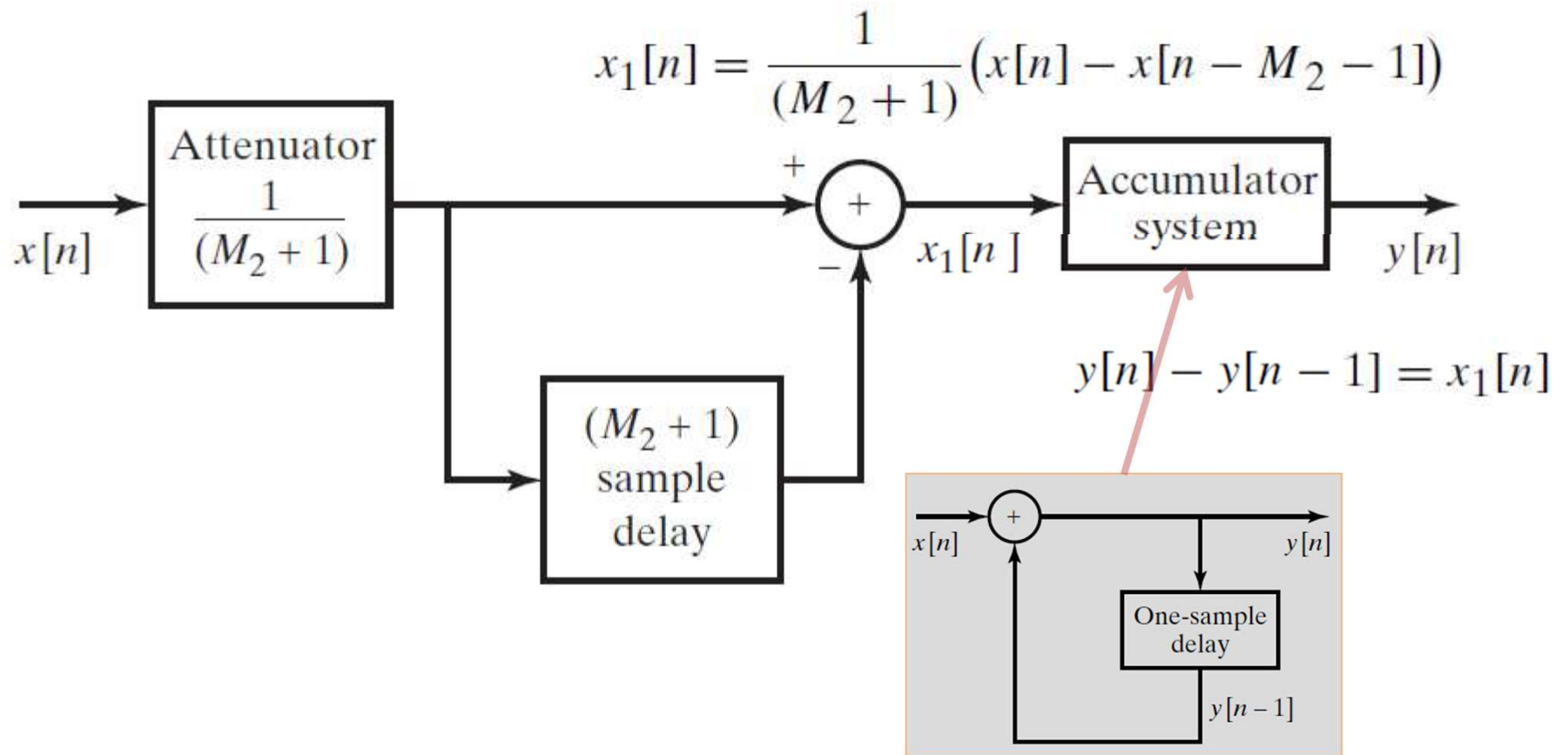
$$y[n] = \frac{1}{(M_2 + 1)} \sum_{k=0}^{M_2} x[n-k]$$

$$h[n] = \frac{1}{(M_2 + 1)} (u[n] - u[n - M_2 - 1])$$

$$y[n] - y[n - 1] = \frac{1}{(M_2 + 1)} (x[n] - x[n - M_2 - 1])$$

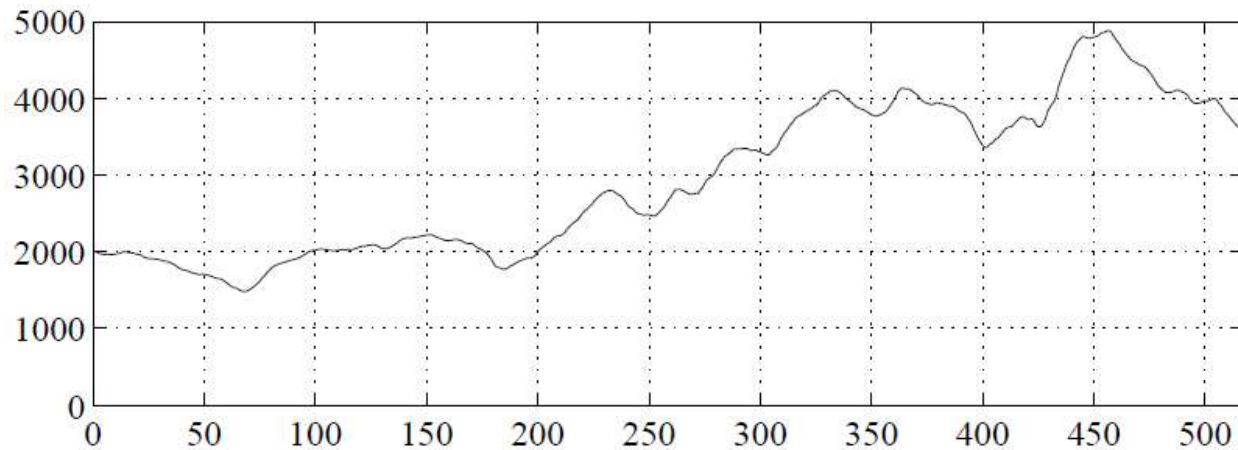
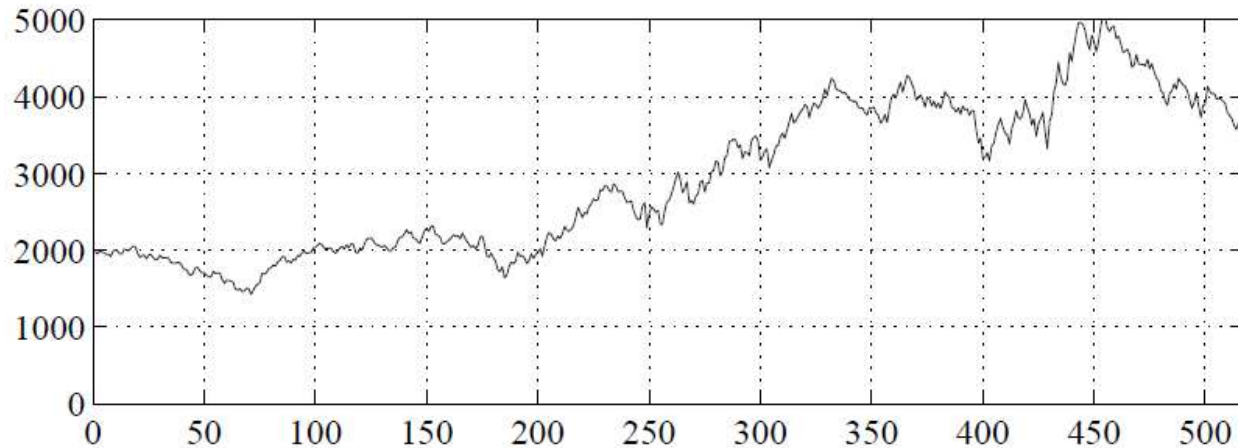
Linear Constant-Coefficient Difference Equations

- Block diagram of the moving-average system:



Linear Constant-Coefficient Difference Equations

- Effect of moving-average system



Linear Constant-Coefficient Difference Equations

- Example: $y[n] = ay[n-1] + x[n]$

$$x[n] = b\delta[n] , y[-1] = 1$$

$$y[0] = a + b \qquad y[-2] = a^{-1}$$

$$y[1] = a^2 + ab \qquad y[-3] = a^{-2}$$

$$y[2] = a^3 + a^2b \qquad y[-4] = a^{-3}$$

$$y[3] = a^4 + a^3b \qquad y[-5] = a^{-4}$$

⋮


⋮

$$y[n] = a^{n+1} + a^n b , n \geq 0$$

$$y[n] = a^{n+1} , n < 0$$

Linear Constant-Coefficient Difference Equations

$$y[n] = a^{n+1} + a^n b, \quad n \geq 0 \qquad y[n] = a^{n+1}, \quad n < 0$$


$$y[n] = a^{n+1} + a^n b u[n]$$

- If $b=0 \rightarrow x[n]=0$, but $y[n]=a^{n+1}$ is not equal to zero.
- Therefore, scaling the input with zero is not gives zero output (the system is not linear).

Linear Constant-Coefficient Difference Equations

- For the shifted input

$$x_1[n] = x[n - n_d] = b\delta[n - n_d]$$

$$y_1[n] = a^{n+1} + a^{n-n_d}bu[n - n_d]$$

$$y_1[n] \neq y[n - n_d]$$

- the system is time variant.

Linear Constant-Coefficient Difference Equations

- If $y[-1]=0$ is given

$$y[n] = a^n b u[n]$$

- The system is linear and time invariant in this case (evaluate with $x[n] = b\delta[n-1]$).
- NOTE: Initial conditions of a LCCDE for systems affect the characteristics directly!
- In general, $x[n]=0$, $n<0$ and initial conditions are chosen as zero for the causal LTI systems.

Linear Constant-Coefficient Difference Equations

- Alternative representation for the accumulator $y[n] = ay[n-1] + x[n]$

$$y[0] = ay[-1] + x[0]$$

$$y[1] = ay[0] + x[1] = a(ay[-1] + x[0]) + x[1] = a^2y[-1] + ax[0] + x[1]$$

$$y[2] = ay[1] + x[2] = a^3y[-1] + a^2x[0] + ax[1] + x[2]$$

⋮

$$y[n] = a^{n+1}y[-1] + \sum_{k=0}^n a^k x[n-k], \quad n \geq 0$$

Response to the initial conditions

Response to the input signal $x[n]$

Linear Constant-Coefficient Difference Equations

- If the system initially relaxed at time $n=0$
 $y[-1]=0$
- Thus a recursive system is relaxed if it starts with zero initial conditions.
- We say that the system is at “**zero state**” in this case.
- The response of the system is called as
“**ZERO STATE RESPONSE**”

$$y_{zs}[n]$$

Linear Constant-Coefficient Difference Equations

$$y_{zS}[n] = \sum_{k=0}^n a^k x[n-k], \quad n \geq 0$$

$$h[n] = a^n u[n] \quad (\text{IIR, causal})$$

Linear Constant-Coefficient Difference Equations

- Suppose that the system is initially nonrelaxed and $x[n]=0$ for all n .
- Then the output of the system with zero input is called the

“ZERO INPUT RESPONSE”

$$y_{zi}[n]$$

$$y_{zi}[n] = a^{n+1} y[-1]$$

Linear Constant-Coefficient Difference Equations

$$y[n] = \alpha^{n+1} y[-1] + \sum_{k=0}^n \alpha^k x[n-k], \quad n \geq 0$$

$$y[n] = y_{zi}[n] + y_{zs}[n]$$