

Chapter 1 Introduction

Learning Objectives

- ◆ Why process signals digitally?
- ◆ Definition of a real-time application.
- ◆ Why use **D**igital **S**ignal **P**rocessing processors?
- ◆ What are the typical **DSP** algorithms?
- ◆ Parameters to consider when choosing a DSP processor.
- ◆ Programmable vs ASIC DSP.
- ◆ Texas Instruments' TMS320 family.

Why go digital?

- ◆ Digital signal processing techniques are now so powerful that sometimes it is extremely difficult, if not impossible, for analogue signal processing to achieve similar performance.
- ◆ Examples:
 - ◆ FIR filter with linear phase.
 - ◆ Adaptive filters.

Why go digital?

- ◆ Analogue signal processing is achieved by using analogue components such as:
 - ◆ Resistors.
 - ◆ Capacitors.
 - ◆ Inductors.
- ◆ The inherent tolerances associated with these components, temperature, voltage changes and mechanical vibrations can dramatically affect the effectiveness of the analogue circuitry.

Why go digital?

- ◆ With DSP it is easy to:
 - ◆ Change applications.
 - ◆ Correct applications.
 - ◆ Update applications.
- ◆ Additionally DSP reduces:
 - ◆ Noise susceptibility.
 - ◆ Chip count.
 - ◆ Development time.
 - ◆ Cost.
 - ◆ Power consumption.

Why NOT go digital?

- ◆ High frequency signals cannot be processed digitally because of two reasons:
 - ◆ Analog to **D**igital **C**onverters, **ADC** cannot work fast enough.
 - ◆ The application can be too complex to be performed in real-time.

Real-time processing

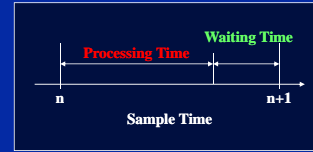
- ◆ DSP processors have to perform tasks in real-time, so how do we define real-time?
- ◆ The definition of real-time depends on the application.
- ◆ Example: a 100-tap FIR filter is performed in real-time if the DSP can perform and complete the following operation between two samples:

$$y(n) = \sum_{k=0}^{99} a(k)x(n-k)$$

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Real-time processing



- ◆ We can say that we have a real-time application if:
 - $\text{Waiting Time} \geq 0$

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Why do we need DSP processors?

- ◆ Why not use a General Purpose Processor (GPP) such as a Pentium instead of a DSP processor?
 - What is the **power consumption** of a Pentium and a DSP processor?
 - What is the **cost** of a Pentium and a DSP processor?

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Why do we need DSP processors?

- ◆ Use a DSP processor when the following are required:
 - Cost saving.
 - Smaller size.
 - Low power consumption.
 - Processing of many "high" frequency signals in real-time.
- ◆ Use a GPP processor when the following are required:
 - Large memory.
 - Advanced operating systems.

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What are the typical DSP algorithms?

- ◆ The Sum of Products (SOP) is the key element in most DSP algorithms:

Algorithm	Equation
Finite Impulse Response Filter	$y(n) = \sum_{k=0}^M a_k x(n-k)$
Infinite Impulse Response Filter	$y(n) = \sum_{k=0}^M a_k x(n-k) + \sum_{k=1}^N b_k y(n-k)$
Convolution	$y(n) = \sum_{k=0}^N x(k)h(n-k)$
Discrete Fourier Transform	$X(k) = \sum_{n=0}^{N-1} x(n) \exp[-j(2\pi/N)nk]$
Discrete Cosine Transform	$F(u) = \sum_{x=0}^{N-1} c(x) f(x) \cos\left[\frac{\pi}{2N}u(2x+1)\right]$

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Hardware vs. Microcode multiplication

- ◆ DSP processors are optimised to perform multiplication and addition operations.
- ◆ Multiplication and addition are done in hardware and in one cycle.
- ◆ Example: 4-bit multiply (unsigned).

Hardware	Microcode
$\begin{array}{r} 1011 \\ \times 1110 \\ \hline 10011010 \end{array}$	$\begin{array}{r} 1011 \\ \times 1110 \\ \hline 0000 \text{ Cycle 1} \\ 1011 \text{ Cycle 2} \\ 1011 \text{ Cycle 3} \\ 1011 \text{ Cycle 4} \\ \hline 10011010 \text{ Cycle 5} \end{array}$

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Parameters to consider when choosing a DSP processor

Parameter	TMS320C6211 (@150MHz)	TMS320C6711 (@150MHz)
Arithmetic format	32-bit	32-bit
Extended floating point	N/A	64-bit
Extended Arithmetic	40-bit	40-bit
Performance (peak)	1200MIPS	1200MFLOPS
Number of hardware multipliers	2 (16 x 16-bit) with 32-bit result	2 (32 x 32-bit) with 32 or 64-bit result
Number of registers	32	32
Internal L1 program memory cache	32K	32K
Internal L1 data memory cache	32K	32K
Internal L2 cache	512K	512K

- ◆ C6711 Datasheet: [\Links\TMS320C6711.pdf](#)
- ◆ C6211 Datasheet: [\Links\TMS320C6211.pdf](#)

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Parameters to consider when choosing a DSP processor

Parameter	TMS320C6211 (@150MHz)	TMS320C6711 (@150MHz)
I/O bandwidth: Serial Ports (number/speed)	2 x 75Mbps	2 x 75Mbps
DMA channels	16	16
Multiprocessor support	Not inherent	Not inherent
Supply voltage	3.3V I/O, 1.8V Core	3.3V I/O, 1.8V Core
Power management	Yes	Yes
On-chip timers (number/width)	2 x 32-bit	2 x 32-bit
Cost	US\$ 21.54	US\$ 21.54
Package	256 Pin BGA	256 Pin BGA
External memory interface controller	Yes	Yes
JTAG	Yes	Yes

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Floating vs. Fixed point processors

◆ Applications which require:

- ◆ High precision.
- ◆ Wide dynamic range.
- ◆ High signal-to-noise ratio.
- ◆ Ease of use.

Need a floating point processor.

◆ Drawback of floating point processors:

- ◆ Higher power consumption.
- ◆ Can be more expensive.
- ◆ Can be slower than fixed-point counterparts and larger in size.

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Floating vs. Fixed point processors

- ◆ It is the application that dictates which device and platform to use in order to achieve optimum performance at a low cost.
- ◆ For educational purposes, use the floating-point device (C6711) as it can support both fixed and floating point operations.

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General Purpose DSP vs. DSP in ASIC

- ◆ Application Specific Integrated Circuits (ASICs) are semiconductors designed for dedicated functions.
- ◆ The advantages and disadvantages of using ASICs are listed below:

Advantages	Disadvantages
<ul style="list-style-type: none"> • High throughput • Lower silicon area • Lower power consumption • Improved reliability • Reduction in system noise • Low overall system cost 	<ul style="list-style-type: none"> • High investment cost • Less flexibility • Long time from design to market

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Texas Instruments' TMS320 family

- ◆ Different families and sub-families exist to support different markets.



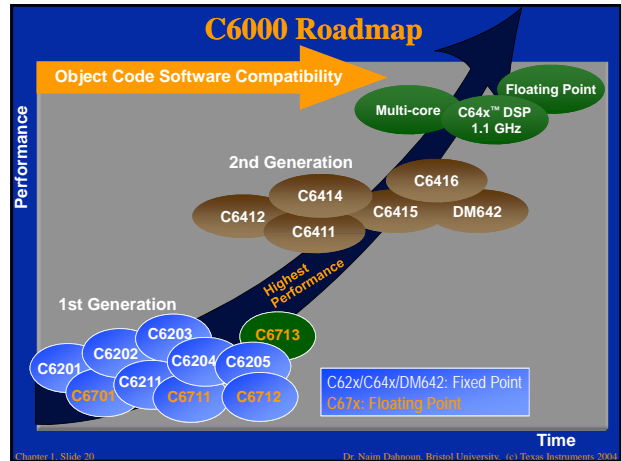
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TMS320C64x: The C64x fixed-point DSPs offer the industry's highest level of performance to address the demands of the digital age. At clock rates of up to 1 GHz, C64x DSPs can process information at rates up to 8000 MIPS with costs as low as \$19.95. In addition to a high clock rate, C64x DSPs can do more work each cycle with built-in extensions. These extensions include new instructions to accelerate performance in key application areas such as digital communications infrastructure and video and image processing.

TMS320C62x: These first-generation fixed-point DSPs represent breakthrough technology that enables new equipments and energizes existing implementations for multi-channel, multi-function applications, such as wireless base stations, remote access servers (RAS), digital subscriber loop (xDSL) systems, personalized home security systems, advanced imaging/biometrics, industrial scanners, precision instrumentation and multi-channel telephony systems.

TMS320C67x: For designers of high-precision applications, C67x floating-point DSPs offer the speed, precision, power savings and dynamic range to meet a wide variety of design needs. These dynamic DSPs are the ideal solution for demanding applications like audio, medical imaging, instrumentation and automotive.



Useful Links

◆ Selection Guide:

- ◆ [\Links\DSP Selection Guide.pdf](#)
- ◆ [\Links\DSP Selection Guide.pdf \(3Q 2004\)](#)
- ◆ [\Links\DSP Selection Guide.pdf \(4Q 2004\)](#)



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